

## Vehicle Electrification System Standards

VII. 3-Phase Power Inverter Systems and Controls

## VII.a Acronyms and Definitions

Image	Name	Acronym	Definition
1.0 Phase 1 Phase 2 Phase 3 0.5 0.5 0.5 1.0 120' 120'	3-Phase		Three Phases are the number of conductor circuits within a motor or generator that are connected in a Wye or Delta configuration.
SW1 SW2 SW2 Three charter for the control of the co	6-Pack Motor Drive		A 6-Pack motor drive circuit contains 6 transistor (typically IGBT) circuits that connect to a source (battery pack) and a 3-Phase electric machine. The 6-Pack drive circuit will be controlled with a sine or 6-step waveform strategy to control the torque and speed of the electric machine
Commutative Woveforms  5 Supp  5 Sunsoidal  0 30 60 90 120 150 160 210 240 270 300 330 360  0.5.  Electrical Degrees	6-Step		The 6-Step (overmodulated) waveform is a derivative of a sine waveform that is used in electric machine control to provide conditions that will permit higher speed operation
Sine Wave	Alternating Current	AC	Alternating current is an electric current which periodically reverses direction, in contrast to direct current which flows only in one direction



NSF / ATE Grant Award # 1700708



0 TIME	Amplitude		Amplitude of a waveform is a direction indication of how much voltage or current is being supplied from a Power Inverter to an electric motor (whether single phase or 3-Phase electric machines).  Amplitude of Voltage or Current correlates, in a linear sense, to how much torque can be developed within an electric machine
	Asymmetrical Waveform		Having parts or aspects that are not equal or equivalent; unequal in some respect. Example: 3-Phase sine waves that are not equal in shape, height, width, etc.
1= Emitter 2= Base 3= Collector	BiPolar Transistor	NPN; PNP	A bipolar junction transistor is a type of transistor that uses both electrons (negative) and holes (positive) charge carriers. Unipolar transistors, such as field-effect transistors, use only one kind of charge carrier
	Buck/Boost Converter (Boost Reactor)		An inductor that uses self-induction to boost battery voltage to a higher level for the purpose of increasing electric machine rpm, torque, and horsepower. The inductor is also used to buck (reduce) electric machine voltage that is transmitted to the battery pack during Regenerative Braking
	Boost Conveter PM INV But IV But IV	Constit Part of the Consti	Buck Blood Camerolar (501 v. Lagereamone Particle and Par





	Bus Bar	A copper or copper alloy bar, with a specified thickness and width that, is bent into a form that will serve as a medium to transfer electrical current from one device/circuit to another
	Bus Capacitor	The dc bus capacitor is the most important passive component in a traction motor drive. Conventional designs have been using a set of electrolytic bulk capacitors to smooth dc bus voltage, reduce waveform harmonics, and increase power factor
Spend Cross of Spend Spe	Bus Discharge Circuit	An electronic circuit that discharges the energy stored in the Bus Capacitors each time the power inverter system is powered OFF (i.e., each time vehicle powered OFF, collision detection or, the opening of the safety interlock circuit when the vehicle is powered ON
Hysteresis band Dand HB Lower band HB Actual current wave  40.5 V <sub>d</sub> 0 Voltage wave	Current Regulation	3-Phase current from the Power Inverter to an electric machine is regulated within the 3-Phase sine waves delivered or received from the electric machine to ensure that current does not exceed the current commanded by the electric machine controller





Hall Effect Current Sensor (2)	(Power Inverter) Current Sensor		A current sensor is a device that detects electric current in a wire (typically Hall Effect design) and generates a signal proportional to that current. The generated output signal could be analog voltage, analog current or digital
	Direct Current	DC	Direct current is the unidirectional flow of an electric charge. An vehicle 12V is a prime example of DC power. Direct current may flow through a conductor such as a wire, but can also flow through semiconductors, insulators, or even through a vacuum as in electron or ion beams
Phasor Diagram of a Sinusoidal Waveform  Vectoristics  100  100  100  100  100  100  100  1	Electrical Degrees		Vector (rotational) and sinusoidal (sine) wave cycles are constructed of 360° increments that comprise 1 cycle
	Electromagnetic Interference (Gasket)	EMI	Electromagnetic shielding is the practice of reducing the electromagnetic field in a space by blocking the field with barriers made of conductive or magnetic materials. EMI shielding is utilized in power electronics gaskets, connectors, wires or, cables
Battery North pole	Electromagnetic Pole		Each of the two points or regions of an artificial or natural magnet to and from which the lines of magnetic force are directed.





	Enclosure (Case)		An electrical enclosure is a cabinet for electrical or electronic components to mount internal parts and to prevent electrical shock to equipment users and protect the contents from the environment. The enclosure is the only part of the equipment which is seen by users
G	Field Effect Transistor	FET	The field-effect transistor is a type of transistor which uses an electric field to control the flow of current. FETs are devices with three terminals: source, gate, and drain
1 Hertz = 1 Cycle Per Second Above and Below the Atomspheric Pressure Line	Frequency (Hertz)	Hz	The SI unit of frequency, equal to one cycle per second.
	Gate Driver		A gate driver is a power amplifier that accepts a low-power input from a controller IC and produces a high-current drive input for the gate of a high-power transistor such as an IGBT or power MOSFET. Gate drivers can be provided either onchip or as a discrete module
The state of the s	Insulation Gate Bipolar Transistor	IGBT	Insulated Gate Bipolar Transistor is a power transistor that has characteristics of both MOSFET and bipolar junction transistors (BJTs). Introduced in the 1980s, the IGBT handles high current, a characteristic of BJTs, but enables fast switching with greater ease of



NSF / ATE Grant Award # 1700708 Northwest Engineering and Vehicle Technology Exchange (NEVTEX)



			control. IGBTs are found in home appliances, electric cars and digital stereo power amplifiers. Modules with multiple IGBTs can support very high voltage and amperage.
Power Inverter Ac  DC  Power Inverter Ac  Ac  Ac  Ac	Invert (an electrical signal)		The inverting of a signal means that it can be changed from one type of signal to another. Example: An AC signal can be inverted from AC to DC or, DC to AC. A Power Inverter changes AC to DC or DC to AC by the use of IGBTs and Rectifier Diodes.
S south parts N north part  S N S N  Affraction  Repulsion	Magnet Pole		Each of the two points or regions of an artificial or natural magnet to and from which the lines of magnetic force are directed.
NO NO	Microcontroller  Motor Controller	MC	A microprocessor-based system (mounted on a printed circuit board with signal conditioning) that controls the torque and speed of an electric machine in HEV, PHEV, BEV, and FCEV Microcontroller Article
30m <sub>H</sub> Som <sup>H</sup> Neutral	Neutral (electric machine)		The common point at which the 3- Phases of an electric machine are connected within a Wye or Delta wound stator
S south pair N north pair  S N S N  Aftraction  Repulsion  Repulsion	North Pole (Magnet or Electromagnet)		1. A permanent magnet is a piece of iron (or an ore, alloy, or other material) that has its component atoms so ordered that the material exhibits properties of magnetism, such as attracting other ironcontaining objects or aligning itself in an external magnetic field. A





			magnet consists of a North and South Pole that can be used to cause electrical or mechanical movement within a component.  2. An electromagnet is a soft metal core made into a magnet by the passage of electric current through a coil surrounding it and will act as a permanent magnet but, it does need electrical current to activate the magnetic fields
0.707a V <sub>PIL</sub> V <sub></sub>	Peak (Sinusoidal Waveform)	Pk	One half (180°) of a full 360° alternating current sine wave
Vrx Vrx Vrr Vrr Vrr Vrr Vrr Vrr Vrr Vrr	Peak-to-Peak (Sinusoidal Waveform)	Pk-Pk	Peak-to-peak (pk-pk) is the difference between the maximum positive and the maximum negative amplitudes of a waveform, as shown below. If there is no direct current ( DC ) component in an alternating current ( AC ) wave, then the pk-pk amplitude is twice the peak amplitude.
Phase shift = 00 degrees A is about of 0 (A feeds* A)  Phase shift = 60 degrees B is about of A (B feeds* A)  Phase shift = 100 degrees A and B waveforms are mirror-images of waveforms are mirror-images of waveforms are not be a feed of the control of the contr	Phase Angle (Phase Shift)		Describes the phase shift between total voltage and total electric current. In the voltage triangle this matches the phase shift between total voltage and active voltage. For the resistance triangle the phase shift lies between the impedance and effective resistance vector. When voltage and current waveforms are superimposed Power Factor is Unity (perfect)





Making sense of power factor. The beer analogy  thread power factor. The beer analogy  Basic a delay one. Why has and pass, or do tool see, a track way of all noting soil. This is the self-of-power power of the factor factor for the self-of-power power of the factor factor factor for the self-of-power power of the factor factor factor factor factor for the self-of-power power of the factor f	Power Factor Correction	PF	Power factor (PF) is the ratio of working power, measured in kilowatts (kW), to apparent power, measured in kilovolt amperes (kVA). Apparent power, also known as demand, is the measure of the amount of power used to run machinery and equipment during a certain period. It is found by multiplying (kVA = V x A). The result is expressed as kVA units. PF expresses the ratio of true power used in a circuit to the apparent power delivered to the circuit. A 96% power factor demonstrates more efficiency than a 75% power factor. PF below 95% is considered inefficient in many regions."
Vehicle Beasers  Beasers  From I beaser Server Inductor Personnel Magnet Beaser Server	Power Inverter Power Inverter Module		A power electronic unit that converts dc electrical power to ac electrical power in single or multiphase systems
50% duty cycle 75% duty cycle 25% duty cycle	Pulse Width Modulation	PWM	Pulse-width modulation (PWM) is a modulation process or technique used in most control systems for encoding the amplitude of a signal right into a pulse width or duration of another signal, usually a carrier signal, for transmission. The purpose of PWM is to control the





			power that is supplied to various types of electrical devices, most especially to inertial loads such as AC/DC motors. PWM is also known as duty cycle
Right Foot Wisel  CANI  Mater  Motor  System  Transmission  Introduction  Introduction  Introduction  Regenerative Braking  Regenerative Braking  Battery  Motor  Transmission  Introduction  Introduction	Regenerative Braking	Regen	Regenerative braking uses an electric vehicle's motor as a generator to convert much of the vehicle kinetic energy lost when decelerating back into stored energy in the vehicle's battery. The generation of electrical power results in negative torque on the vehicle axle causing its speed to slow (braking effect). The rate of vehicle speed reduction is determined by a significant number of factors in the powertrain and battery pack system. The next time the car accelerates, it uses much of the energy previously stored from regenerative braking instead of tapping in further to its own energy reserves.
Anode Cathode (-)	Rectifier Diode		"A diode allows current in only one direction. It can be used to "rectify" AC current into a DC current (i.e., an alternator operates with positive and ground or 0V negative to charge a 12V vehicle battery). Such a diode can also be used to prevent current from flowing in the "wrong" direction in a circuit."
0.707a	Root-Mean- Square	RMS	A calculation of an average used in statistics and engineering, abbreviated as RMS. To find the root mean square of a set of numbers, square all the numbers in





		the set and then find the arithmetic Mean of the squares. Take the square root of the result. This is the root mean square. It is also amount of AC power that produces the same heating effect as an equivalent (or useable) DC power. RMS is calculated as RMS = (P-P)(.3535) or RMS = (P)(0.707)
+	Self-Induction	The property of the coil due to which it opposes the change of current flowing through it. Inductance is attained by a coil due to the self-induced emf produced in the coil itself by changing the current flowing through it.
1.0 Phase 1 Phase 2 Phase 3  0.5 120° 120° 120° 120° 120° 120° 120° 120°	Sine Wave (3- Phase) Sinusoidal Waveform	A circuit, system, or device that magnetically energizes or is energized by three electromotive forces that are separated by 120° sine wave cycles.
S south parter IX routh parter  S N S N  Attraction  Regulation  Regulation	South Pole (Magnet or Electromagnet)	1. A permanent magnet is a piece of iron (or an ore, alloy, or other material) that has its component atoms so ordered that the material exhibits properties of magnetism, such as attracting other ironcontaining objects or aligning itself in an external magnetic field. A magnet consists of a North and South Pole that can be used to cause electrical or mechanical





		movement within a component.  2. An electromagnet is a soft metal core made into a magnet by the passage of electric current through a coil surrounding it and will act as a permanent magnet but, it does need electrical current to activate the magnetic fields
1.0 Phase 1 Phase 2 Phase 3 0.5 0.5 0.5 1.0 120' 120' 120'	Symmetrical (Waveform)	Similarity or exact correspondence between different things. With respect to 3-Phase AC waveforms, symmetry would indicate that all 3 waveforms within one cycle would be identical (symmetrical shape)
340 Bast slat compand	Thermal Grease	Thermal grease is printed onto the IGBT or, other power modules or the cooling fin, and the force exerted by tightening the screws that secure the IGBT module to the cooling fin causes the thermal grease to spread out and fill the gap between the IGBT module and cooling fin. The thermal grease will transfer heat from a power electronic device to the mounting surface. The heat sink system is either a mounting surface utilizes heat sink fins or liquid coolant routed through an enclosure to remove high temperatures from the power electronic device



To comment or offer suggestions on this standard, contact Ken Mays:

Ken Mays	NEVTEX
541-383-7753	kmays@cocc.edu



